

UNIVERSITY OF WATERLOO  
FACULTY OF ENGINEERING  
Department of Electrical &  
Computer Engineering

ECE 204 *Numerical methods*

**Approximating the solution  
to algebraic equations**

Douglas Wilhelm Harder, LEL, M.Math.  
dwharder@waterloo.ca  
dwharder@gmail.com

CC BY NC SA


1

Approximating solutions to algebraic equations

## Introduction


- In this topic, we will
  - Describe what will be covered in the next topic
    - Approximating solutions to algebraic equations
  - Introduce some of the terminology
  - Introduce the approaches that will be used
  - Describe the upcoming lectures

2


Approximating solutions to algebraic equations 

## Solutions to equations

- In elementary school, you learned to solve a simple linear equation  $ax = b$ 
  - In secondary school, you learned how to solve quadratic equations:
 
$$ax^2 + bx^2 + c = 0$$
  - However, there are simple equations that have no exact solution
 
$$x^5 + x^2 + 1 = 0$$
- There are more complex equations, as well:
 
$$\sin(x^2) - x^2\cos(x) + 1 = \cos(x + \sin(x)) + 5$$


 3

3


Approximating solutions to algebraic equations 

## Linear and non-linear equations

- A linear equation in one or more variables is any equation that can be written in the form
 
$$a_1x_1 + a_2x_2 + \cdots + a_nx_n = b$$
- Any equation that is not a linear equation is a *non-linear* equation:
 
$$\sin(x^3 + 1) + x^2 - 1 = 0$$

 4


4

Approximating solutions to algebraic equations 


## Systems of equations

- In linear algebra, you learned to solve a system of  $n$  linear equations in  $n$  unknowns  $\mathbf{Ax} = \mathbf{b}$
- You could have a system of non-linear equations
 
$$x^2 + 2xy + 3y = 4$$

$$x^2 - 5 = 3y + 5y^2$$
  - A solution is any pair  $(x, y)$  that satisfies both these equations
- Given a system of equations where at least one is non-linear, we will describe them as a system of non-linear equations
- In general, having  $n$  unknowns requires  $n$  equations
  - Each equation provides one further constraint

5 


5

Approximating solutions to algebraic equations 

## Root-finding problems

- Any equation can be rewritten as a root-finding problem:
  - Solving  $\sin(x^5) - x^2\cos(x) + 1 = \cos(x + \sin(x)) + 5$  is equivalent to solving
 
$$\sin(x^5) - x^2\cos(x) + 1 - \cos(x + \sin(x)) - 5 = 0$$
- Any system of equations can be rewritten as a root-finding problem
  - Turn each equation into a root-finding problem
 
$$x^2 + 2xy + 3y - 4 = 0$$

$$x^2 - 5 - 3y - 5y^2 = 0$$
  - We are finding the root of a vector-valued function of a vector variable:
 
$$\mathbf{f}(\mathbf{u}) = \begin{pmatrix} u_1^2 + 2u_1u_2 + 3u_2 - 4 \\ u_1^2 - 5 - 3u_2 - 5u_2^2 \end{pmatrix}$$


6 

6

Approximating solutions to algebraic equations

## Root-finding problems

- Apart from linear equations and systems of linear equations, we will reformulate all equations to be a root-finding problem and thus find algorithms for:
  - Approximating a solution to a non-linear equation in one variable
  - Approximating a solution to a system of  $n$  non-linear equations in  $n$  variables
- The first we will write as  $f(x) = 0$  where
  - $f$  is a real- or complex-valued function of a real or complex variable, respectively
- The second we will write as  $\mathbf{f}(\mathbf{x}) = \mathbf{0}$  where:
  - $\mathbf{x}$  is an  $n$ -dimensional vector
  - $\mathbf{f}$  is a vector-valued function of a vector variable


7 

7


Approximating solutions to algebraic equations


## Approximating solutions to equations

- We will assume you know how to solve  $ax = b$
- We will start by approximating solutions to a non-linear equation of one variable with:
  - Newton's method
  - The bisection method
  - The bracketed secant method
  - The secant method
- We have already discussed partial pivoting and the Jacobi method
  - The Gauss-Seidel method
  - Successive over-relaxation
- We will generalize Newton's method for approximating a solution to a system of  $n$  non-linear equations in  $n$  unknowns

8 


8



Approximating solutions to algebraic equations 


## Quadratic equations


- However, we will start with finding a solution to a quadratic equation



9


9



Approximating solutions to algebraic equations 


## Summary


- Following this topic, you now
  - Have an overview of the ideas to be covered in this topic
  - Know how to describe equations as being linear or non-linear
  - Understand that we will use different approaches for each:
    - Matrix-vector equations for linear equations
    - Root-finding problems for non-linear equations



10


10




Approximating solutions to algebraic equations 


## References

- [1] [https://en.wikipedia.org/wiki/System\\_of\\_linear\\_equations](https://en.wikipedia.org/wiki/System_of_linear_equations)
- [2] [https://en.wikipedia.org/wiki/Nonlinear\\_system](https://en.wikipedia.org/wiki/Nonlinear_system)

11 


11



Approximating solutions to algebraic equations 

## Acknowledgments

None so far.

12 


12

Approximating solutions to algebraic equations

## Colophon

These slides were prepared using the Cambria typeface. Mathematical equations use Times New Roman, and source code is presented using Consolas. Mathematical equations are prepared in MathType by Design Science, Inc. Examples may be formulated and checked using Maple by Maplesoft, Inc.

The photographs of flowers and a monarch butter appearing on the title slide and accenting the top of each other slide were taken at the Royal Botanical Gardens in October of 2017 by Douglas Wilhelm Harder. Please see <https://www.rbg.ca/> for more information.



13

13

Approximating solutions to algebraic equations

## Disclaimer

These slides are provided for the ECE 204 *Numerical methods* course taught at the University of Waterloo. The material in it reflects the author's best judgment in light of the information available to them at the time of preparation. Any reliance on these course slides by any party for any other purpose are the responsibility of such parties. The authors accept no responsibility for damages, if any, suffered by any party as a result of decisions made or actions based on these course slides for any other purpose than that for which it was intended.

14

14